MODELS TSS & TSL

TSS

TSL
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SAFETY SYMBOLS

The following symbols are used in this document to alert the reader to areas of potential hazard:

**DANGER** indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.

**WARNING** indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

**CAUTION** identifies a hazard which could lead to damage to the machine, damage to other equipment and/or environmental pollution. Usually an instruction will be given, together with a brief explanation.

**NOTE** is used to highlight additional information which may be helpful to you.

SAFETY CONSIDERATIONS

The equipment covered in this manual is designed for safe and reliable operation when installed and operated within its design specification limits. To avoid personal injury or damage to equipment or property while installing or operating this equipment, it is essential that qualified, experience personnel familiar with local codes and regulations, perform these functions using good judgment and safe practices. See the following cautionary statements.

**ELECTRICAL SHOCK HAZARDS**

All power must be disconnected prior to installation and servicing this equipment. More than one source of power may be present. Disconnect all power sources to avoid electrocution or shock hazards.

**HOT PARTS HAZARD**

Electric resistance heating elements must be disconnected prior to servicing. Electric heaters may start automatically; disconnect all power and control circuits prior to servicing to avoid burns.

Check that rigging and lifting equipment can safely support the unit assembly and component weights.

**WARNING**

All assemblies must be adequately secured during lifting and rigging by temporary supports and restraints until equipment is permanently fastened and set in its final location.

All unit temporary and permanent supports must be capable of safely supporting the equipment’s weight and any additional live, seismic or dead loads that may be encountered. All supports must be designed to meet applicable local codes and ordinances.

All fastening devices must be designed to mechanically lock the assembly in place without the capability of loosening or breaking away due to system operation and vibration.

Secure all dampers when servicing damper, actuators or linkage. Dampers may activate automatically, disconnect the control circuits or pneumatic control systems to avoid injury.

Protect adjacent flammable material when brazing. Use flame and heat protection barriers where needed. Have fire extinguisher ready for immediate use.
INSPECTION
Upon receipt of equipment, carefully check all items against the bill of lading to ensure that all equipment has been received (including shipped loose items). Note any discrepancy on the bill of lading before signing.

Inspect all equipment for any signs of damage caused during transit. On units with re-heat, check the coil fins and/or ensure that the resistance heat coils are not damaged. Note any visual damage on the bill of lading before signing. Immediately report all visual and concealed damage to the carrier and file a claim with the carrier.

Locate the model number on the nameplate and check that the correct units have been received. Verify that all options have been included, such as controls, heating coils, etc. Also ensure that unit voltage agrees with the building parameters. If a discrepancy is discovered between what was ordered and received, contact your local Johnson Controls representative immediately.

DO NOT USE FLOW SENSOR, CONNECTING TUBES, COIL STUBOUTS OR DAMPER SHAFT AS A HANDLE WHEN LIFTING OR MOVING EQUIPMENT, AS DAMAGE MAY OCCUR.

DO NOT HANDLE EQUIPMENT’S HEATING ELEMENTS, AS PERMANENT DAMAGE MAY OCCUR.

CHECK assembly and component weights to be sure that the rigging equipment can handle them safely. Note; also check the centers of gravity and any specific rigging instructions.

CHECK for adequate ventilation so fumes do not migrate through ductwork to occupied spaces when welding or cutting around the unit.

DO NOT work on damper until associated actuator is disconnected.

NEVER pressurize equipment above specified test pressure.

PROTECT adjacent flammable materials when brazing. Use flame and heat protection barriers where needed. Have a fire extinguisher at hand and ready for immediate use.

STORAGE
If equipment is to be stored prior to installation, observe the following precautions:

1. Choose a dry storage site that is reasonably level and sturdy to prevent undue stress or permanent damage to the equipment. Set equipment off ground if in moisture prone areas.

2. Tag and store in a safe place until needed. Cover entire equipment with protective tarp or moisture proof cover. Extend cover under equipment if stored on ground. Secure cover with adequate tie downs and store indoors. Be sure that piping connections have protective shipping caps installed.
PRE-INSTALLATION INSPECTION

**DO NOT USE FLOW SENSOR, CONNECTING TUBES, COIL STUBOUTS OR DAMPER SHAFT AS A HANDLE WHEN LIFTING OR MOVING EQUIPMENT, AS DAMAGE MAY OCCUR.**

**DO NOT HANDLE EQUIPMENT’S HEATING ELEMENTS, AS PERMANENT DAMAGE MAY OCCUR.**

Ensure that all linkages are connected properly. Check the linkage that connects the actuator to the damper shaft to ensure that the nuts are tight.

While viewing the damper from the discharge of the unit, rotate the shaft fully. The damper should close fully and there should be no gaps between the damper gasketing and the inside of the valve.

SEQUENCE OF OPERATION

**Single Duct**

The basic unit consists of a sheet metal casing and an air valve, which is used to modulate the air being delivered into the occupied zone. Air enters the air valve inlet and exits into the sheet metal casing to be distributed to the occupied zone through ductwork attached to the discharge of the unit.

The basic unit can be ordered with either a factory mounted hot water heating coil or an electric heater.

These re-heat units are used primarily to reheat the air-to-zone temperature when the load in the occupied space drops off.

The primary air is modulated through the FlowStar™ air valve by rotating the damper blade. The air valves come in rectangular and round. The round valves only come in diameters of 4, 5, 6, 8, 10, 12, 14 and 16 inches; an adapter must be used for metric ductwork.

INSTALLATION

**DO NOT USE FLOW SENSOR, CONNECTING TUBES, COIL STUBOUTS OR DAMPER SHAFT AS A HANDLE WHEN LIFTING OR MOVING EQUIPMENT, AS DAMAGE MAY OCCUR.**

**DO NOT HANDLE EQUIPMENT’S HEATING ELEMENTS, AS PERMANENT DAMAGE MAY OCCUR.**

All terminal equipment with electric heaters must be installed in a horizontal plane with respect to the airflow stream. Low height equipment (Model TSL) can be flipped over in the field to vary or change control section handing.

Clearances

All equipment covered in this document, including those with electric heat, are ETL listed for 0.0” clearance to combustibles. Refer to NEC and/or local codes for minimum electrical clearances required for service. Equipment should not make contact with any structure located above the equipment without appropriate isolation. Equipment supplied with bottom access panels requires sufficient clearance to access fasteners, and to lower and slide panel horizontally until clear of bottom of unit.

**Hanging and Mounting Equipment**

Although the basic equipment is generally light enough that it can be supported by the ductwork, Johnson Controls strongly recommends that all equipment be suspended from the upper most ceiling or a structural element of the building, independent of the false ceiling grid. Suspension devises are field supplied, sized and designed by others. Johnson Controls will not accept responsibility for unit support. Equipment must be installed in a level horizontal plane. Failure to level equipment properly may prevent proper operation of controls. Provisions for proper support in seismically active regions is the responsibility of others. See table 1 through 4 for unit weights.
UNIT WEIGHTS

When requested, equipment is supplied with optional hanger brackets for use with up to a 3/8" diameter hanger rod. See submittal drawings for hanger bracket locations.

Hanger straps may be utilized as an alternate means of suspending the equipment. Do not secure hanger straps to electric heaters, coils or control enclosures. Hanger straps can be mounted directly to the sides and bottom of equipment casing, such that they do not interfere with working components or access panels, using screws that do not penetrate the unit cabinet more than 3/8".

When hanging equipment, always use the support method as prescribed for rectangular duct in the job specifications.

Duct Connections

When fastening ductwork to equipment, DO NOT use fasteners that penetrate equipment cabinet more than 3/8" [10mm]. Fasteners penetrating the equipment cabinet over 3/8" [10mm] may come in contact with live electrical parts or penetrate other components within the equipment casing causing damage.

All duct connections should be configured and installed in accordance with SMACNA guidelines and all local code requirements.
Allow a minimum of 1½-duct diameters of straight duct prior to equipment inlet and equipment discharge. The diameter of the inlet duct for round valves must be equal to the listed size of the equipment. The round air valve inlet collar of the equipment is 1/8" smaller then listed size in order to allow the round ductwork to slip over the air valve inlet collar. DO NOT INSERT DUCTWORK INTO AIR VALVE INLET COLLAR. When making ductwork connection to air valve inlet collar and insulating air valve inlet, take caution not to damage or remove the flow sensor connections, which are vital to unit control. Provide insulation around entire inlet collar (all the way to the equipment casing).

Permissible discharge duct connections are straight flanged, slip and drive or drive and screw.

If equipment is to be installed in a location with high humidity, external insulation around the heating coil should be installed.

**Sound Critical Applications**

Flexible duct connectors are not recommended on equipment discharge. The sagging membrane of these fittings can cause turbulence and higher air velocities that generate noise. Also, lightweight membrane material allows noise to breakout, which can increase sound levels in the space below.

**Coil Connections**

Hot water and steam coils are male sweat connections. Use appropriate brazing alloy for system temperature and pressure. Refer to unit construction submittal drawing for specific connection size. MAXIMUM HYDRONIC SYSTEM OPERATING PRESSURE MUST NOT EXCEED 300 PSIG. MAXIMUM STEAM SYSTEM PRESSURE MUST NOT EXCEED 15 PSIG.

**Electrical**

All field wiring must comply with NEC and all local codes. Electrical and/or control wiring diagrams are located on the control enclosure box. All electric heaters are staged per specifications.

The installing electrician should rotate the incoming electric service by phase to help balance the building electrical load.

Minimum circuit ampacity (MCA) designates the maximum operating load of the equipment for sizing wire feeders. Fuse size of the internal fuse if supplied. Maximum Overcurrent Protection (MOP) designates the largest breaker or fuse in the electrical service panel that can be used to protect the equipment.

Use Copper conductors only.

**OPERATION**

**Start-Up**

Thorough safety precautions should always be taken when performing startup and service. Only qualified individuals should perform these tasks.

Check that all electrical work is finished and properly terminated. Check that all electrical connections are tight and that the proper voltage is connected.

**3 Phase Balancing**

AC power imbalance must not exceed 2%. Be sure that the following guides are met:

1. AC power is within 10% of rated voltage at rated frequency. *(See equipment nameplate for ratings).*
2. AC power is within 5% of rated frequency at rated voltage.
3. A combined variation in the voltage and frequency of 10% (sum of absolute values) of rated values, provided the frequency variation does not exceed 5% of rated frequency.

*Equipment with electric heat requires a minimum of 0.1" w.g. downstream static pressure.*

Prior to start-up, the project control sequence/wiring diagram should be obtained and thoroughly understood. If factory supplied analog or DDC controls are utilized, refer to the applicable Operation Manual for start-up and balancing information.
MAINTENANCE

Optional Damper Actuator

An optional factory mounted floating type actuator is available, which mounts directly to the damper operating shaft. The actuator is not provided with and does not require any limit switches but is electronically protected against overload.

Manual Override

A button on the side of the actuator cover disengages the gear train so the drain shaft can be moved manually. Releasing the button will re-engage the gear train.

Mechanical Angle of Rotation Stops

The adjustable stops may be field adjusted to halt the rotation of the damper blade before the damper blade reaches the damper stops. The actuator can be indefinitely stalled in any position without harm.

1. Loosen the two end stop screws using a No. 2 Phillips head screwdriver, being careful not to unscrew the captive nut under the slot.
2. Move the stops (in 2.5° steps) to the desired position and retighten the screws.

External Terminal Strip

The external terminal strip is located on the top of the actuator. Connections are numbered. The terminals are designed for 26 to 16 gauge wires. For most installations, 18 or 16 gauge wire will work well with the actuator (see Table 5 for maximum wire lengths).

Checkout Instructions

1. Disconnect actuator from the controller.
2. Apply 24 VAC to the COM and CW terminals on the actuator. Actuator should rotate in a clockwise direction.
3. Apply 24 VAC to the COM and CCW terminals on the actuator. Actuator should rotate in a counter clockwise direction.
4. If actuator moves in both directions, it is operational.
5. If the actuator does not rotate, it may be at an end stop or there is a problem with the damper.
6. Loosen the set screw to free the actuator from the damper shaft. Check to make sure that the damper shaft rotates freely.
7. Check to make sure that actuator is not against stop. Repeat steps 2 and 3.
8. If actuator does not rotate, replace.

Damper Shaft

There is an indicator on the end of the damper shaft that can be used to determine the position of the damper blade. If the indicator is horizontal, the damper is completely open. The damper shaft is ½” diameter.

Coil

The frequency of required cleaning is dependent on the operating hours of the system, filter maintenance and efficiency as well as dirt load.

<table>
<thead>
<tr>
<th>TABLE 5 - MAXIMUM WIRE LENGTHS</th>
</tr>
</thead>
<tbody>
<tr>
<td>WIRE SIZE</td>
</tr>
<tr>
<td>-----------</td>
</tr>
<tr>
<td>16 GA</td>
</tr>
<tr>
<td>18 GA</td>
</tr>
<tr>
<td>20 GA</td>
</tr>
<tr>
<td>22 GA</td>
</tr>
</tbody>
</table>

Important: Coils may become externally dirty as result of normal operation. Dirt on the surface of the coil reduces its ability to transfer heat that can result in reduced performance, and increased operating energy cost. If the dirt on the surface of the coil becomes wet, microbial growth (mold) can result, possibly causing unpleasant odors and serious health related indoor air quality problems.

Fin edges are sharp. Fins are fragile; care must be exercised to avoid damaging fins. Do not use solutions to clean coils; drain pans are not present to remove collected solution.

Overload Protection

The actuators are electronically protected against mechanical overload. In the actuator, an electronic circuit maintains the current at a level that will not damage the motor while providing adequate holding torque.
**Cleaning**

1. Disconnect all electrical power to the equipment, tag and lock out power source.
2. Gain access to coil either through ductwork or optional coil access panel.
3. Use soft brush and vacuum to remove loose debris from sides of coil. Do not use fluid or solvents to clean coils, as no provisions for collecting liquids exist on this type of equipment.
4. Straighten any coil fins that may have been damaged during cleaning process with fin comb.
5. Replace ductwork or access panel and restore electrical power to equipment.

**Electric Heat**

Johnson Controls electric heaters require little or no maintenance.

Electric heaters come equipped with a primary auto-reset limit switch. These limit switches provide protection against overheating. The auto-reset limits switches automatically cut the heater off when overheating occurs, and turns the heater back on when the elements have cooled down. Electric heaters also come equipped with a secondary one-time trip limit switch. Should the secondary limit switches trip, they will need to be replaced with a limit switch that has the same trip temperature as the one-time trip limit switch that was originally supplied with the electric heater. An optional manual reset secondary is available, which can be reset by depressing the reset switch.

**Minimum Operating Conditions**

Airflow must be at least 70 CFM per kW. A minimum of 0.1" w.g. external pressure is required.

**Electric Heater Rack Replacement**

**JOHNSON CONTROLS HEATERS**

1. Turn off power supply before servicing.
2. Locate T-Plate inside on heater control enclosure.
3. Before removing wires from the element rack T-Plate, mark where the wires are connected so that they can be reconnected correctly on the new element rack.
4. Remove the wires and screws holding the heater T-plate in the control enclosure and remove element rack.
5. Insert new element rack into control enclosure and replace screws to secure the element rack to control enclosure.
6. Replace wires.
7. Close control enclosure cover before turning on the power.

**Electric Heater Element Replacement**

**TUTCO HEATERS**

1. Turn off power supply before servicing.
2. Disconnect field wiring from Electric Heater Control Enclosure.
3. Disconnect Amp Plug Connectors if equipped.
4. Remove 4 mounting screws from inside Electric Heater Control Enclosure.
5. Slide entire heater assembly out of Single Duct Terminal.
6. Remove wires and any jumpers from heater element terminal ends, noting which wire and jumper goes to which terminal.
7. Remove ¼" hex head screws located near terminal ends.
8. Remove ¼" hex head screws from opposite of terminal end on heater rack.
9. Remove elements and replace with new ones.
10. Reassemble, replace wires correctly.
11. Close control enclosure cover before turning on power.
# ELECTRIC HEATER TROUBLESHOOTING GUIDE

**JOHNSON CONTROLS AND TUTCO**

## TABLE 6 - HEATER TROUBLESHOOTING GUIDE

Check wiring diagrams to ensure that heater is properly wired.

<table>
<thead>
<tr>
<th>SYMPTOM</th>
<th>POSSIBLE CAUSE</th>
<th>CORRECTIVE ACTION</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>HEATER DOES NOT OPERATE</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>No Power</td>
<td>Check Disconnect.</td>
<td>Check Disconnect.</td>
</tr>
<tr>
<td>No Control Voltage</td>
<td>Check Control Signal (i.e. 24 VAC).</td>
<td>Check Control Signal (i.e. 24 VAC).</td>
</tr>
<tr>
<td>Blown Fuse</td>
<td>Check transformer and transformer fusing (if applicable), replace if necessary.</td>
<td>Check transformer and transformer fusing (if applicable), replace if necessary.</td>
</tr>
<tr>
<td>Open Limit (primary or secondary)</td>
<td></td>
<td>Replace fuse.</td>
</tr>
<tr>
<td>Airflow Incorrect Direction</td>
<td>Check sensing tube, rotate if needed.</td>
<td>Replace limits or reset as applicable.</td>
</tr>
<tr>
<td>Low Airflow Static Pressure</td>
<td>Increase airflow.</td>
<td>Check for continuity across limit to determine if open, replace as necessary.</td>
</tr>
<tr>
<td>Damaged Elements</td>
<td>Check for open or damaged elements and replace as necessary.</td>
<td>Check for open or damaged elements and replace as necessary.</td>
</tr>
<tr>
<td><strong>LOW OR HIGH TEMPERATURE RISE</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Incompatible Thermostat or Controller</td>
<td>Check Wiring.</td>
<td>Check Wiring.</td>
</tr>
<tr>
<td>Problems with Additional Stages</td>
<td>Check location of thermostat; may be installed in a “too hot” or “too cold location. Check heat outputs on controller.</td>
<td>Check location of thermostat; may be installed in a “too hot” or “too cold location. Check heat outputs on controller.</td>
</tr>
<tr>
<td>Incorrect CFM</td>
<td>Check for blocked duct or location of heater.</td>
<td>Check for compatibility.</td>
</tr>
<tr>
<td><strong>SHORT CYCLING</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Improper Airflow</td>
<td>Check for even airflow across the face of the element section.</td>
<td>Check for even airflow across the face of the element section.</td>
</tr>
<tr>
<td>Low CFM</td>
<td>See remedies for “Improper Airflow”.</td>
<td>Check for even airflow across the face of the element section.</td>
</tr>
<tr>
<td><strong>HEATER WITH SSR DOES NOT OPERATE</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Incorrect Signal Applied</td>
<td>Verify signal input.</td>
<td>Verify signal input.</td>
</tr>
<tr>
<td>Interface Board Fuse Blown</td>
<td>Replace fuse.</td>
<td>Replace fuse.</td>
</tr>
<tr>
<td><em>See SSR Troubleshooting (next page)</em></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Lethal voltages are present in the heater control enclosure. Use extreme caution when taking measurements in these units. Always disconnect power before removing or re-applying any connections.

1. Before applying power, verify wiring matches diagram in cover of heater control enclosure, and that correct line voltage has been wired to heater line block.

2. Verify 24 VAC +15% or -10% between P1 and P2 of interface circuit board (ETPHCI, ETPHCV2, etc., depending on input).

3. The table below lists responses to input signal by interface model as explained in step 4. If any of these inputs cannot be obtained, refer to the literature on the device that is supposed to provide the input. Otherwise, proceed to step 4.

<table>
<thead>
<tr>
<th>INTERFACE MODEL</th>
<th>“PULSE” INPUT</th>
<th>FULL OFF INPUT</th>
<th>FULL ON INPUT</th>
<th>INPUTS</th>
</tr>
</thead>
<tbody>
<tr>
<td>ETPHCI</td>
<td>12.0 mA</td>
<td>4.0 mA</td>
<td>20.0 mA</td>
<td>Sig, Com</td>
</tr>
<tr>
<td>ETPHCV2</td>
<td>6.0 VDC</td>
<td>2.0 VDC</td>
<td>10.0 VDC</td>
<td>Sig, Com</td>
</tr>
<tr>
<td>ETPHCC</td>
<td>50%</td>
<td>0 VAC</td>
<td>24 VAC</td>
<td>Sig, Com</td>
</tr>
<tr>
<td>ETPHCC1</td>
<td>50%</td>
<td>0 VAC</td>
<td>24 VAC</td>
<td>+18, Com</td>
</tr>
</tbody>
</table>

4. Apply Full Off Input per table above. If the unit is three phase, verify that the LED on the SSR (solid state relay) is off. If the unit is single phase, measure voltage between P4 and P6 and verify 0.3 VDC + or - 0.3 VDC. Replace the interface circuit board if the voltage is higher than specified, or the LED is on.

5. Apply Full On Input per table above. If the unit is three phase, verify that the LED on the SSR (solid state relay) is on. If the unit is single phase, measure voltage between P4 and P6 and verify between 3 and 5 VDC.

6. If the module provided is an ETPHCC or ETPHCC1, go to step 7. Apply “Pulse” Input per table above. If the unit is three phase, verify that the LED on the SSR (solid state relay) is flashing at an interval of about one second. If the unit is single phase, the voltage between P4 and P6 of the interface board should vary between the Full Off and Full On voltages in steps 4 and 5 in intervals of about one second.

Some voltmeters will not respond this quickly, so the value of the voltages may not appear to be correct; however, if the voltage appears to be changing at regular intervals, it may be assumed that this function is operating properly.

This completes the low voltage portion of the unit test. Go to step 8.

7. For the ETPHCC or ETPHCC1, the associated consignment controller must be directed to output a 50% On pulse width modulation signal. For three phase, verify that the LED is pulsing at regular intervals. The rate of the pulse is based on the output from the consignment controller. If the unit is single phase, the DC voltage between P4 and P6 of the interface board should vary between the full Off and full On voltages in steps 4 and 5.

Some voltmeters will not respond this quickly, so the value of the voltages may not appear to be correct; however, if the voltage appears to be changing at regular intervals, it may be assumed that this function is operating properly.
8. If the heater always remains energized when power is applied, remove the wire from P4 of the interface circuit board. If the heat remains on, there is a wiring error or the SSR is defective.

Remove Power From the Unit Before Proceeding With the Next Step.

9. If the heater is always de-energized when power is applied, remove the line and load connections to the proportional heat control and temporarily tie them together. If the system is a three phase arrangement, do the phases one at a time.

Always remove power from the unit before moving to the next phase.

Make sure there is no danger of the temporary connection shorting to another component or the chassis. Briefly reapply power. If the section of heat under test now energizes, the SSR is defective. If heater still will not energize, one of the heater safety devices (limits, safety contactor or airflow switch) or elements is defective.
PROPORTIONAL HEAT CONTROL
(SSR) TROUBLESHOOTING GUIDE
Tutco Heaters, All Power Modules

- Install the ammeter on the line voltage input wire of heater.
- This is your primary source of information to know if the heater is operative or not.
- A multimeter set in Ohms cannot be used to confirm that the high voltage contact of a power module is closed.
- You cannot confirm R820 power module operation unless a load is applied.

NO DEMAND, ex. 277 Vac

WITH 100 % HEATING DEMAND, ex. 277 Vac

| TUTCO HEATER INTERFACE |
PROPORTIONAL HEAT CONTROL
(SSR) TROUBLESHOOTING GUIDE
Tutco Heaters, R820 SCR’s

NO DEMAND, ex. 480 Vac

Control Signal 2 to 10 Vdc
Under 2 Vdc = 0% capacity

Control Signal 4 to 20 mA
Under 4 mA = 0% capacity

Control Signal 0 to 135 Ohms
Under 0 Ohms = 0% capacity

WITH 100 % HEATING DEMAND, ex. 480 Vac

Control Signal 2 to 10 Vdc
Over 10 Vdc = 100% capacity

Control Signal 4 to 20 mA
Over 20 mA = 100% capacity

Control Signal 0 to 135 Ohms
Over 135 Ohms = 100% capacity

R820 SCR
1 Common
2 24 Vac
3 Input Dip Switch

Fuses

Element

Ammeter

0 Vac

480 Vac

Between 5-30 Vdc

Full rated current
FlowStar Calibration Chart
(For dead-end differential pressure transducers)

Probe Differential Pressure (inches w.g.)

UNIT SIZE | 400 SERIES (PNEUMATIC) STANDARD CONTROLLER | 7000 SERIES ANALOG ELECTRONIC | DDC CONSIGNMENT CONTROLS (See Notes Below)
| 0.015 | 0.03 | 0.05 | 1.0 | 1.5|
| 4 | 43 | 250 | 35 | 250 | 30 | 43 | 55 | 250 | 250 |
| 5 | 68 | 350 | 50 | 350 | 48 | 65 | 88 | 350 | 350 |
| 6 | 75 | 490 | 60 | 550 | 53 | 75 | 97 | 435 | 530 |
| 8 | 145 | 960 | 115 | 1000 | 105 | 145 | 190 | 840 | 1000 |
| 10 | 235 | 1545 | 185 | 1600 | 165 | 235 | 305 | 1355 | 1600 |
| 12 | 340 | 2250 | 285 | 2300 | 240 | 340 | 440 | 1975 | 2300 |
| 14 | 475 | 3100 | 390 | 3100 | 335 | 475 | 615 | 2750 | 3100 |
| 16 | 625 | 4100 | 520 | 4100 | 440 | 625 | 805 | 3595 | 4100 |
| 19 | 1180 | 6500 | 1025 | 6500 | 845 | 1180 | 1510 | 6375 | 6500 |
| 22 | 1730 | 8000 | 1450 | 8000 | 1260 | 1730 | 2200 | 8000 | 8000 |

Notes:
1. Minimum and maximum airflow limits are dependent on the specific DDC controller supplied. Contact the control vendor to obtain the minimum and maximum differential pressure limits (inches w.g.) of the transducer utilized with the DDC controller.
2. Maximum CFM is limited to value shown in General Selection Data.
3. FlowStar™ differential pressure tubing connections: High side indicated by red tubing; Low side indicated by black tubing.
4. Electric heat will not operate below 0.03” w.g. differential pressure.
FlowStar Calibration Chart
(For dead-end differential pressure transducers)

Model TSL

NOTE: Maximum and minimum CFM limits are dependent on the type of controls that are utilized. Refer to the table below for specific values. When DDC controls are furnished by others, the CFM limits are dependent on the specific control vendor that is employed. After obtaining the differential pressure range from the vendor, the maximum and minimum CFM limits can be obtained from the chart to the left (many controllers are capable of controlling minimum setpoint down to 0.015" w.g.)

<table>
<thead>
<tr>
<th>UNIT SIZE</th>
<th>400 SERIES (PNEUMATIC) STANDARD CONTROLLER</th>
<th>7000 SERIES ANALOG ELECTRONIC</th>
<th>DDC CONSIGNMENT CONTROLS (See Notes Below)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>MIN.</td>
<td>MAX.</td>
<td>MIN.</td>
</tr>
<tr>
<td>10</td>
<td>235</td>
<td>1545</td>
<td>170</td>
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<tr>
<td>12</td>
<td>340</td>
<td>2250</td>
<td>240</td>
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<tr>
<td>14</td>
<td>495</td>
<td>3100</td>
<td>350</td>
</tr>
<tr>
<td>16</td>
<td>660</td>
<td>4100</td>
<td>465</td>
</tr>
</tbody>
</table>

Notes:
1. Minimum and maximum airflow limits are dependent on the specific DDC controller supplied. Contact the control vendor to obtain the minimum and maximum differential pressure limits (inches w.g.) of the transducer utilized with the DDC controller.
2. Maximum CFM is limited to value shown in General Selection Data.
3. FlowStar™ differential pressure tubing connections: High side indicated by red tubing; Low side indicated by black tubing.
4. Electric heat will not operate below 0.03" w.g. differential pressure.